

**Amendments to the Specification:**

**Please replace the paragraphs starting on page 12, line 8 and ending on page 13, line 21 with the following paragraphs:**

The conveyer width adjusting rollers 31b and 41b are installed at a predetermined position of the conveyer guide frames 31a and 41a, the conveyer lifting members 31c and 41c are installed on the bottom of the inside thereof, and the conveyer driving units 31d and 41d are installed at an inner sidewall thereof. The conveyer guide frames 31a and 41a guide the carried printed circuit board. The conveyer width adjusting rollers 31b and 41b ~~may be~~ are used for guiding the conveyer guide frames 31a and 41a when adjusting the width of the conveyer guide frames 31a and 41a according to the width of the printed circuit board. In case of mounting parts on the printed circuit board, the conveyer lifting members 31c and 41c lift/lower the printed circuit board at a predetermined height so that the head unit 13 can mount the parts. To mount parts, the conveyer driving units 31d and 41d generate the driving force for carrying the printed circuit board, which is then lifted to a predetermined height by the ~~conveyor~~ conveyer lifting members 31c and 41c for the mounting of parts, and then lowered as the ~~conveyor~~ conveyer lifting members 31c and 41c are lowered when parts mounting is complete. By this driving force, the printed circuit board is moved along the conveyer guide frames 31a and 41a.

To receive the printed circuit board being moved along the conveyer guide frames 31½ and 41a, the first horizontal driving device 32 and the second horizontal driving device 42 are installed respectively at the bottom of the conveyer guide frames 31a and 41a. As the first and

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second driving devices 32 and 42, a linear motor is used, which consists of movers 32a and 42a provided with armature coils 32b and 42b and stators 32c and 42c having a plurality of permanent magnets 32d and 42d arranged therein. The linear motor horizontally moves the conveyer guide frames 31a and 41a in a predetermined direction according to an electric signal supplied from a drive circuit 62 by control of a controller 61 and arranges the ~~conveyor~~ conveyer guide frames 31a and ~~31b~~ 41a in the width of the first transfer 20 and the second transfer 50. Here, the linear motor is one of a coil mover linear motor and a permanent magnet mover linear motor (not shown). Besides the linear motor, a ball screw driving device (not shown) or a timing belt driving unit (not shown) can be selected.